

REVISION CLASS 1

Aidan Hogg - 21 November 2019
ELEC96010 (EE3-07): Digital Signal Processing
Department of Electrical and Electronic Engineering

Method:

- 1: Conceptual question posed - students think quietly on their own and report initial answers on Mentimeter (3 mins)
- 2: Students discuss their answers in small groups (2 mins)
- 3: Explanation/discussion of correct answer (3 mins)

Consider the following statements:

- 1: Allpass filters have mirror image numerator and denominator coefficients
- 2: In an allpass filter, the zeros are the poles reflected in the unit circle
- 3: Allpass filters have a gain magnitude of 1 even with coefficient errors

Which of these statements are true?

- A: 1
- B: 1 and 2
- C: All 3 of them

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Allpass filters have mirror image numerator and denominator coefficients

$$b[n] = a[N - n] \quad \Leftrightarrow \quad B(z) = z^{-N} A(z^{-1})$$

$$H(e^{j\omega}) = \frac{\sum_{r=0}^M b[r]e^{-j\omega r}}{\sum_{r=0}^M b[r]e^{-j\omega(M-r)}} = e^{j\omega M} \frac{\sum_{r=0}^M b[r]e^{-j\omega r}}{\sum_{r=0}^M b[r]e^{j\omega r}}$$

$$\Rightarrow \quad |H(e^{j\omega})| \equiv 1 \forall \omega$$

Allpass filters have a gain magnitude of 1 even with coefficient errors

First Order:

$$H(z) = \frac{-p + z^{-1}}{1 - pz^{-1}} = -p \frac{1 - p^{-1}z^{-1}}{1 - pz^{-1}}$$

Poles at p and zero at p^{-1} : 'reflected in unit circle'

Constant distance ratio $|e^{j\omega} - p| = |p| |e^{j\omega} - \frac{1}{p}| \forall \omega$

Consider the following system:

$$y[n] = 2x[n] - 3x[n - 1] + x[n - 2]$$

Where are the poles and zeros located?

- | | |
|---|----------------------------------|
| A: Zeros at $z = \{2, 0\}$ and $\{1, 0\}$ | Poles at $z = \{0, 0\} \times 2$ |
| B: Zeros at $z = \{2, 0\}$ and $\{1, 0\}$ | Pole at $z = \{0, 0\}$ |
| C: Zeros at $z = \{1/2, 0\}$ and $\{1, 0\}$ | Poles at $z = \{0, 0\} \times 2$ |

Consider the following system:

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B: Zeros at $z = \{2, 0\}$ and $\{1, 0\}$ Pole at $z = \{0, 0\}$
C: **Zeros at $z = \{1/2, 0\}$ and $\{1, 0\}$** **Poles at $z = \{0, 0\} \times 2$**

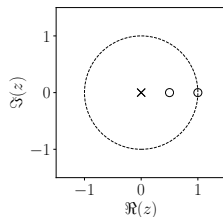
Solution

$$y[n] = 2x[n] - 3x[n-1] + x[n-2]$$

$$Y(z) = 2X(z) - 3z^{-1}X(z) + z^{-2}X(z)$$

$$Y(z) = [z^{-2} - 3z^{-1} + 2]X(z)$$

$$Y(z) = [(z^{-1} - 2)(z^{-1} - 1)]X(z)$$



Therefore

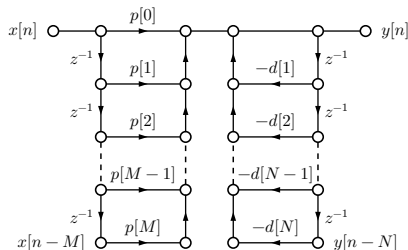
$$\text{Zeros at } z = \left\{ \frac{1}{2}, 0 \right\} \text{ and } \left\{ 1, 0 \right\}$$

$$\text{Poles at } z = \left\{ 0, 0 \right\} \text{ and } \left\{ 0, 0 \right\}$$

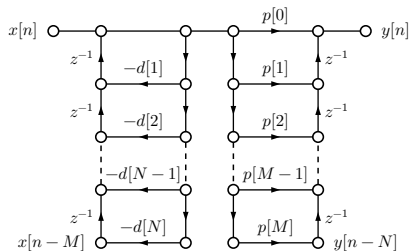
Consider the filter:

$$H(z) = \frac{p[0] + p[1]z^{-1} + \dots + p[M]z^{-M}}{1 + d[1]z^{-1} + \dots + d[N]z^{-N}}$$

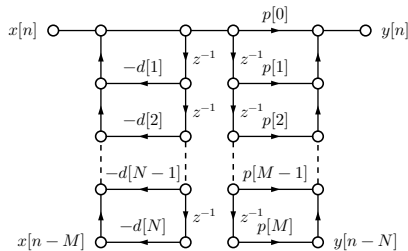
Which digital filter structure is implementing Direct Form I Transposed?



A



B

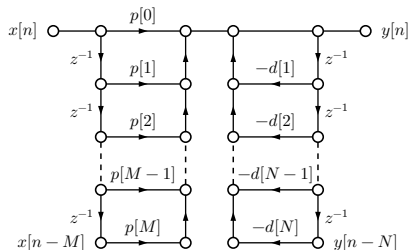


C

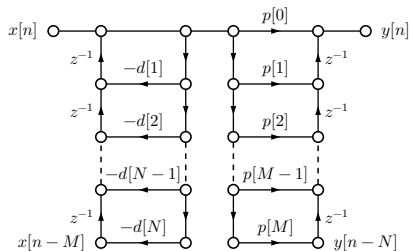
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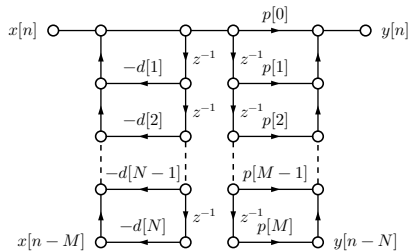
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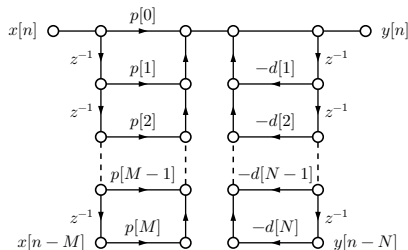
C

EXPLANATION

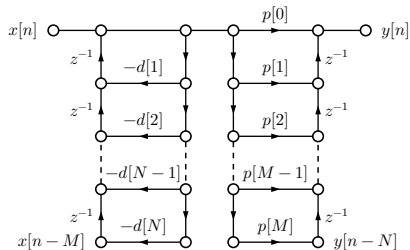
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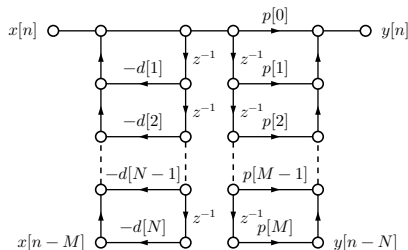
Which digital filter structure is implementing Direct Form I Transposed?



Direct Form I



Direct Form I Transposed



Direct Form II

If an IIR filter has a transfer function:

$$H(z) = \frac{P(z)}{D(z)} = \frac{p[0] + p[1]z^{-1} + p[2]z^{-2} + \dots + p[M-1]z^{-(M-1)} + p[M]z^{-M}}{1 + d[1]z^{-1} + d[2]z^{-2} + \dots + d[N-1]z^{-(N-1)} + d[N]z^{-N}}$$

Then direct forms use coefficients $d[k]$ and $p[k]$ directly. This can be implemented as a cascade of two filter sections where:

$$H_1(z) = \frac{W(z)}{X(z)} = P(z) = p[0] + p[1]z^{-1} + p[2]z^{-2} + \dots + p[M-1]z^{-(M-1)} + p[M]z^{-M}$$

$$H_2(z) = \frac{Y(z)}{W(z)} = \frac{1}{D(z)} = \frac{1}{1 + d[1]z^{-1} + d[2]z^{-2} + \dots + d[N-1]z^{-(N-1)} + d[N]z^{-N}}$$

Note that $H_1(z)$ can be seen as an FIR filter and the time-domain representation of $H_2(z)$ is given by:

$$y[n] = w[n] - d[1]y[n-1] - d[2]y[n-2] - \dots - d[N]y[n-N]$$

Direct form I can be viewed as $P(z)$ followed by $\frac{1}{D(z)}$.

Direct form II implements $\frac{1}{D(z)}$ followed by $P(z)$

Transposed Forms

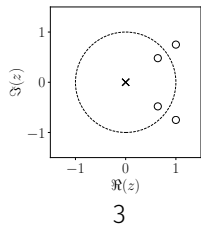
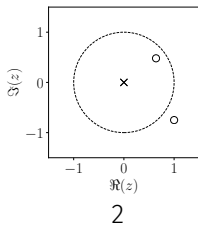
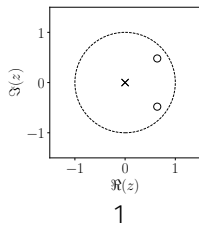
It is also possible to convert any structure into an equivalent transposed form. This is achieved in the following way:

- 1: Reverse direction of each interconnection
- 2: Reverse direction of each multiplier
- 3: Change junctions to adders and vice-versa
- 4: Interchange the input and output signals

Check: A valid structure must never have any feedback loops that don't go through a delay (z^{-1} block).

An FIR filter $B(e^{j\omega})$ is determined by the zeros of

$$z^M B(z) = \sum_{r=0}^M b[M-r]z^r$$

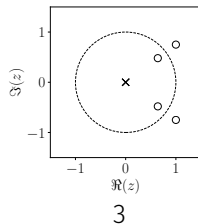
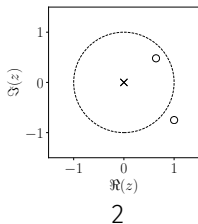
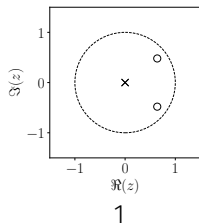


Which FIR filter has symmetric coefficients $b[n]$?

- A: 1 and 3
- B: 2 and 3
- C: 3

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Which FIR filter has symmetric coefficients $b[n]$?

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Symmetric properties:

Real $b[n] \Rightarrow$ conjugate zero pairs: $z \Rightarrow z^*$

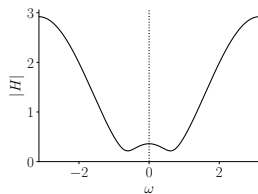
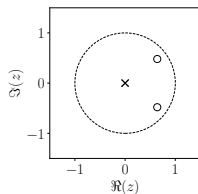
Symmetric: $b[n] = b[M - n] \Rightarrow$ reciprocal zero pairs: $z \Rightarrow z^{-1}$

Real & Symmetric $b[n] \Rightarrow$ conjugate and reciprocal groups of four (else pairs on the real axis)

EXPLANATION

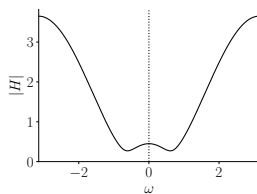
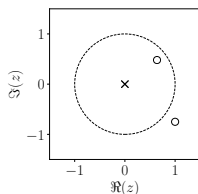
Real

$[1, -1.28, 0.64]$



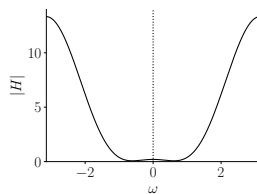
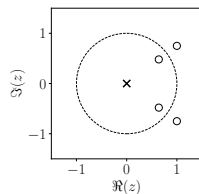
Symmetric

$[1, -1.64 + 0.27j, 1]$



Real & Symmetric

$[1, -3.28, 4.7625, -3.28, 1]$



In all of the proofs below, we assume that $z = z_0$ is a root of $B(z)$ so that $B(z_0) = \sum_{r=0}^M b[r]z_0^{-r} = 0$ and then we prove that this implies that other values of z also satisfy $B(z) = 0$.

(1) Real $b[n]$

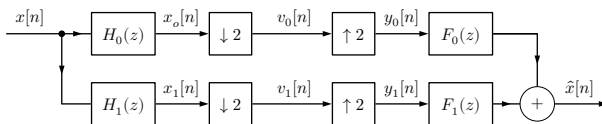
$$\begin{aligned} B(z_0^*) &= \sum_{r=0}^M b[r](z_0^*)^{-r} \\ &= \sum_{r=0}^M b^*[r](z_0^*)^{-r} && \text{sine } b[r] \text{ is real} \\ &= \left(\sum_{r=0}^M b[r]z_0^{-r} \right)^* && \text{take complex conjugate} \\ &= 0^* = 0 && \text{since } B(z_0) = 0 \end{aligned}$$

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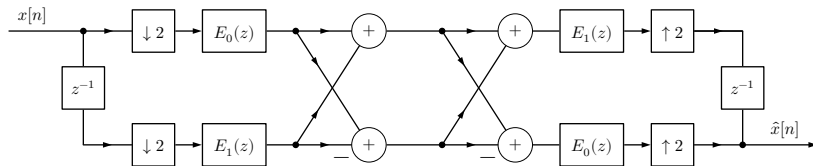
(2) Symmetric: $b[n] = b[M - n]$

$$\begin{aligned}
 B(z_0^{-1}) &= \sum_{r=0}^M b[r]z_0^r \\
 &= \sum_{n=0}^M b[M - n]z_0^{M-n} && \text{substitute } r = M - n \\
 &= z_0^M \sum_{n=0}^M b[M - n]z_0^{-n} && \text{take out } z_0^M \text{ factor} \\
 &= z_0^M \sum_{n=0}^M b[n]z_0^{-n} && \text{since } b[M - n] = b[n] \\
 &= z_0^M \times 0 = 0 && \text{since } B(z_0) = 0
 \end{aligned}$$

Consider the following Quadrature Mirror Filterbank (QMF):



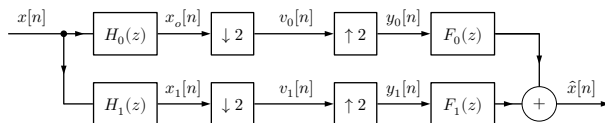
Which can be implemented using polyphase QMF:



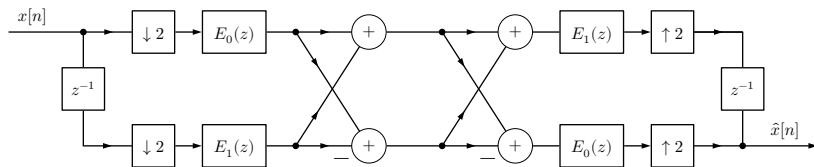
What is the computational saving achieved by the polyphase QMF?

- A: A factor of 2
- B: A factor of 4
- C: A factor of 8

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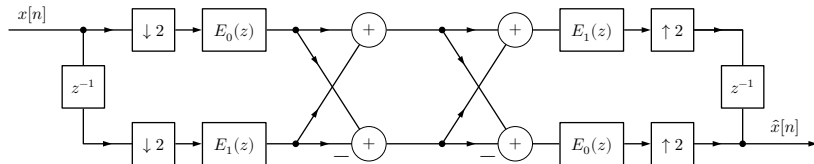
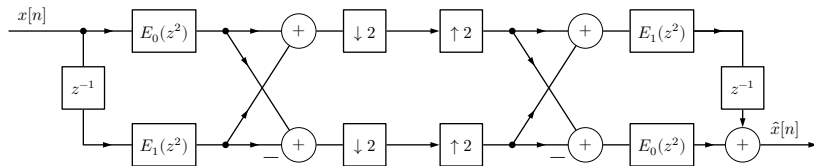
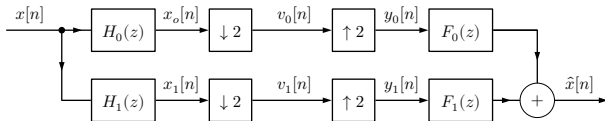
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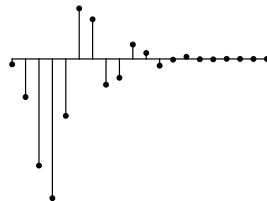
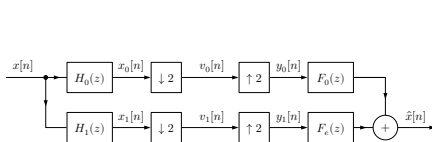
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EXPLANATION

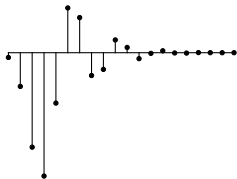


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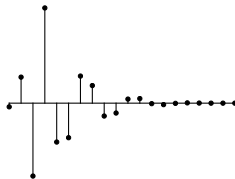


Impulse response $h_0[n]$

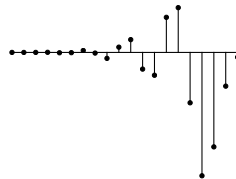
Which is the correct impulse response for $h_1[n]$?



A

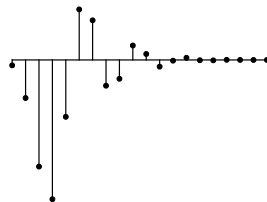
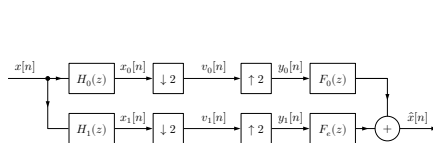


B



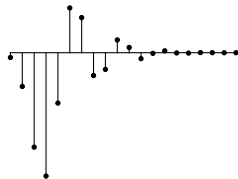
C

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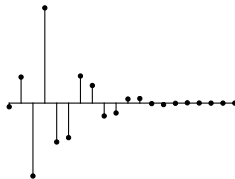


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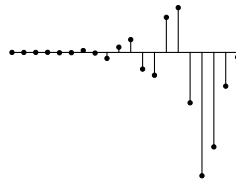
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A

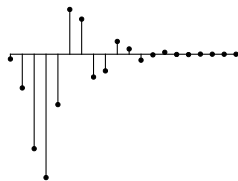
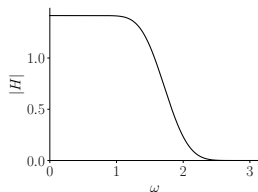


B

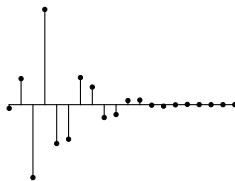
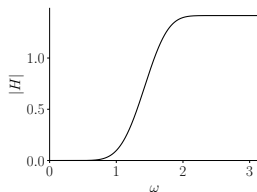


C

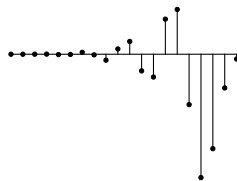
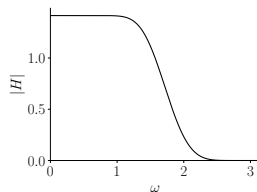
Magnitude responses:



$$h_1[n] = h_0[n]$$

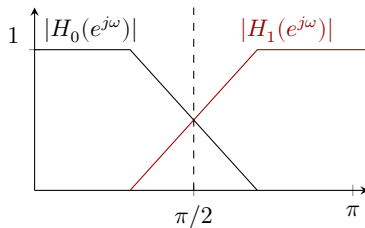


$$h_1[n] = (-1)^n h_0[n]$$



$$h_1[n] = h_0[N-1-n]$$

Proof:



The relationship between $H_0(z)$ and $H_1(z)$ when they are quadrature mirror filters is $H_1(z) = H_0(-z)$.

The corresponding relationship between the impulse responses of these filters is $h_1[n] = (-1)^n h_0[n]$.

$$H_1(z) = H_0(-z) = \sum_{n=-\infty}^{\infty} h_0[n](-z)^{-n} = \sum_{n=-\infty}^{\infty} h_0[n](-1)^n z^{-n}$$

There will be a class next Thursday (Week 9 - 28/11/2019)

Room: 403A/B

Time: 15:00 to 16:00