## Imperial College London

## MODULE 5 CLASS

Aidan Hogg - 14 November 2019
ELEC96010 (EE3-07): Digital Signal Processing
Department of Electrical and Electronic Engineering

## PEER INSTRUCTION

Method:
1: Conceptual question posed - students think quietly on their own and report initial answers on Mentimeter (3 mins)
2: Students discuss their answers in small groups (2 mins)
3: Explanation/discussion of correct answer (3 mins)

Consider the following resampling cascades:

Equality 1 :


Equality 2 :


Equality 3: $\quad \uparrow Q=H\left(z^{Q}\right)-\downarrow Q=+\quad+$
Which equality statements are true?
A: 3
B: 1 and 3
C: All of them

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## GO TO WWW.MENTI.COM AND USE THE CODE 497447

The signal $y[m]$ is obtained by upsampling $x[n]$ by a factor of 3 .



Which is the correct frequency spectrum for $y[m]$ ?




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Consider the following resampling cascades which preserves information:


What cutoff frequency $\omega_{c}$ must the LPF have to preserve information while changing the sampling rate?

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\begin{aligned}
& \text { A: } \omega_{c}=\pi \\
& \text { B: } \omega_{c}=\frac{\pi}{20} \\
& \text { C: } \omega_{c}=\frac{\pi}{21}
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Consider the following system


What is the correct expression for the output $y[n]$
A: $y[n]=\left\{\begin{aligned} x[(2 n / 3)-6], & n=0, \pm 3, \pm 6, \cdots \\ 0, & \text { otherwise }\end{aligned}\right.$
B: $y[n]=\left\{\begin{aligned} x[(3 n / 2)-1], & n=0, \pm 4, \pm 8, \cdots \\ 0, & \text { otherwise }\end{aligned}\right.$
$C: y[n]=\left\{\begin{aligned} x[(3 n / 2)-6], & n=0, \pm 4, \pm 8, \cdots \\ 0, & \text { otherwise }\end{aligned}\right.$

## ANSWER

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## EXPLANATION



Thus $u[n]=x[6 n], v[n]=u[n-1]=x[6 n-6]$ and
$y[n]=\left\{\begin{array}{cl}v[n / 4], & n=0, \pm 4, \pm 8, \cdots \\ 0, & \text { otherwise }\end{array}=\left\{\begin{array}{cl}x[(3 n / 2)-6], & n=0, \pm 4, \pm 8, \cdots \\ 0, & \text { otherwise }\end{array}\right.\right.$

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Which is the correct spectrum of the output?




## ANSWER

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Filtering should always be performed at the lowest possible sampling rate, therefore, what is the actual computational saving that can be achieved by doing this?

A: $K$
B: $\frac{K}{2}$
C: $\frac{K}{4}$

Hint: Think about the polyphase decomposition of the complete filter:


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Hint: Think about the polyphase decomposition of the complete filter:


## POLYPHASE DOWNSAMPLER

$$
x^{x[n]}+H(z)-\downarrow K{ }^{v[i]}
$$



## POLYPHASE UPSAMPLER

$\stackrel{v[i]}{\uparrow K} H^{y(z)}$


