

Tutorial Problem Sheet 9

Question 1. Consider the discrete-time system

$$\begin{aligned}x_{k+1} &= \begin{bmatrix} 1 & -2 \\ 3 & -1 \end{bmatrix} x_k + \begin{bmatrix} 1 \\ -1 \end{bmatrix} u_k, \\ y_k &= \begin{bmatrix} 3 & -1 \end{bmatrix} x_k.\end{aligned}$$

- (a) Show that the system is observable.
- (b) Design an asymptotic observer where both eigenvalues of $A + LC$ are zero and with state \hat{x}_k , such that $e_k = x_k - \hat{x}_k = 0$ for all $k \geq N$. Determine the smallest value of N for which the above condition can be satisfied.
- (c) Let $u_k = K\hat{x}_k + v_k$ with $K = [3/4, 3/4]$.
Write the equations of the closed-loop system, with state $[x_k, \hat{x}_k]$, input v_k and output y_k , and determine the eigenvalues of this system.

Question 2. Consider the continuous-time system

$$\begin{aligned}\dot{x} &= \begin{bmatrix} 1 & -2 \\ 3 & -1 \end{bmatrix} x + \begin{bmatrix} 1 \\ -1 \end{bmatrix} u, \\ y &= \begin{bmatrix} 3 & -1 \end{bmatrix} x\end{aligned}$$

- (a) Design an asymptotic observer with a double pole at -6 .
- (b) Suppose x_0 is the observer state evaluated in part 1. Let $u = Kx_0 + v$ with $K = [-4, 2]$.
Compute the eigenvalues of the closed-loop system.

Question 3. Consider the continuous-time system $\dot{x} = Ax$, $y = Cx$. Let

$$A = \begin{bmatrix} 0 & 1 \\ 0 & -2 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 0 \end{bmatrix}.$$

- (a) Show, using PBH test, that the system is observable.
- (b) Design an asymptotic observer for the system. Select the output injection gain L such that the matrix $A + LC$ has two eigenvalues equal to -3 .
- (c) Suppose that one can measure $y(t)$ and a delayed copy of $y(t)$ given by $y(t - \tau)$, with $\tau > 0$.

For $t \geq \tau$, express the vector $Y(t) = \begin{bmatrix} y(t) \\ y(t - \tau) \end{bmatrix}$ from $x(0)$.

Show that the relation determined above can be used, for any $\tau > 0$, to compute $x(0)$ as a function of $Y(t)$, where $t \geq \tau$. Argue that the above result can be used to determine $x(t)$ from $Y(t)$, for $t \geq \tau$, exactly.